

Extended Formulations for Radial Cones

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Joint work with

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Combinatorial optimization problem:

- ▶ Ground set E (finite)
- ▶ Feasible solutions $\mathcal{F} \subseteq 2^E$
- ▶ Objective vector $c \in \mathbb{Q}^E$
- ▶ Goal: minimize cost $c(F) := \sum_{e \in F} c_e$ over all $F \in \mathcal{F}$.

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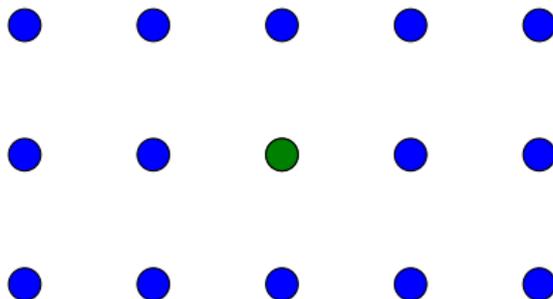
- ▶ Given $F \in \mathcal{F}$, determine optimality or find $F' \in \mathcal{F}$ with $c(F') < c(F)$.

Theorem (Schulz, Weismantel & Ziegler, 1995; Grötschel & Lovász, 1995)

*We can solve the augmentation problem (for arbitrary objective vectors) in polynomial time **if and only if** we can solve the optimization problem (for arbitrary objective vectors) in polynomial time.*

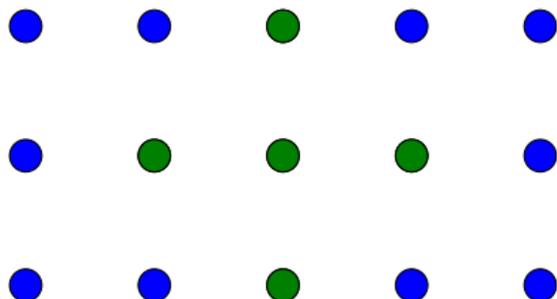
Polyhedral method:

- Identify $F \in \mathcal{F}$ with $\chi(F) \in \{0, 1\}^E$ s.t. $\chi(F)_e = 1 \iff e \in F$.



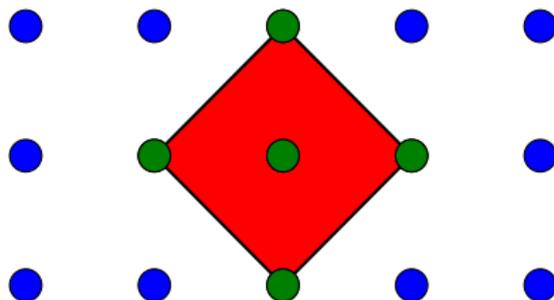
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- ▶ Optimization problem is then to minimize $\langle c, x \rangle$ over $x \in X$.



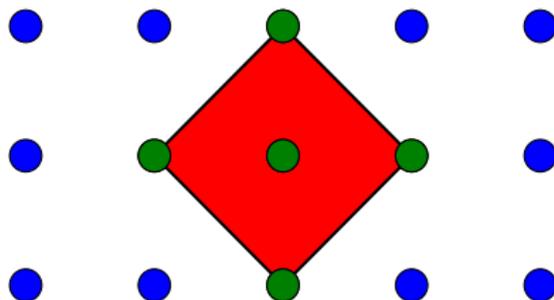
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- ▶ Optimization problem is then to minimize $\langle c, x \rangle$ over $x \in \text{conv}(X)$.
- ▶ Find an outer description of $\text{conv}(X)$, i.e., $\text{conv}(X) = \{x \in \mathbb{R}^E : Ax \leq b\}$.
- ▶ Optimization problem is now an LP and we can use black-box solvers.



One drawback of the polyhedral method:

- ▶ Consider $X := \{x \in \{0, 1\}^n : \sum_{i=1}^n x_i \text{ even}\}$.
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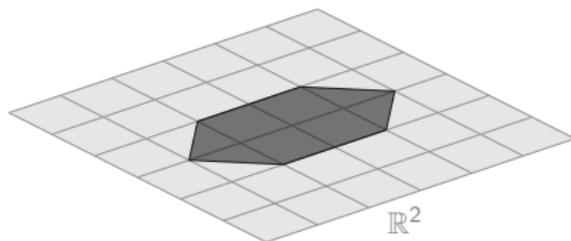
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- ▶ $P = \text{conv}(X)$ has many facets, but maybe there exists an **extension** (Q, π) ($Q \subseteq \mathbb{R}^d$ polyhedron, $\pi : \mathbb{R}^d \rightarrow \mathbb{R}^n$ linear with $P = \pi(Q)$) with **few facets**?



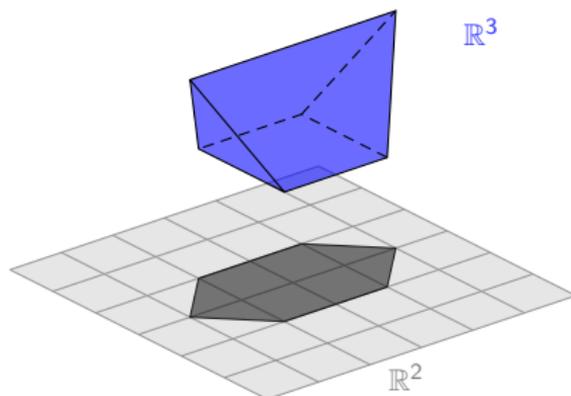
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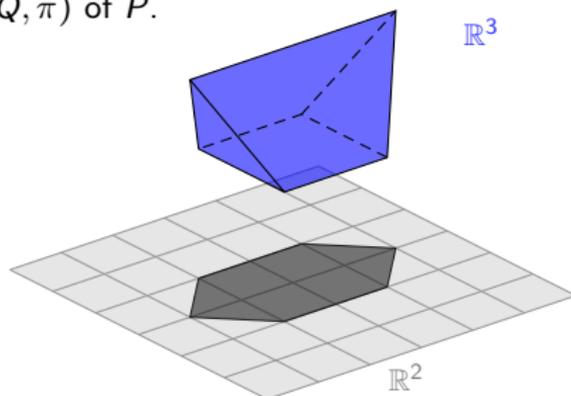
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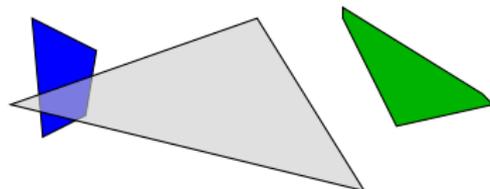
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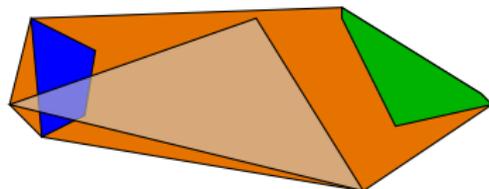
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- ▶ Applying the theorem: $\text{xc}(\text{conv}(X)) \leq \mathcal{O}(n^2)$

Hard problems:

- ▶ Max-Cut problem: cut polytope for K_n (complete graph with n nodes) has extension complexity $2^{\Omega(n)}$ (Fiorini, Massar, Pokutta, Tiwary & de Wolf, 2012), best bound is 1.5^n (Kaibel & Weltge, 2013).

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- ▶ A perfect matching in a graph $G = (V, E)$ is a set $M \subseteq E$ with $|M \cap \delta(v)| = 1$.
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Theorem (Rothvoss, 2013)

For every even n , $\text{xc}(P_{\text{pmatch}}(n)) \geq 2^{\Omega(n)}$. Here, $P_{\text{pmatch}}(n)$ denotes the perfect matching polytope for K_n .

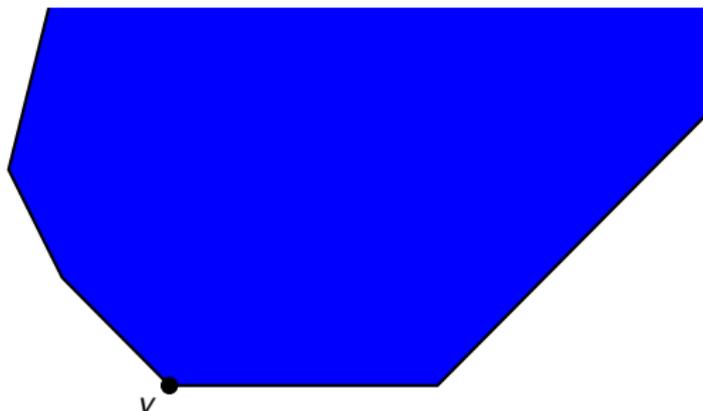
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- ▶ Consider a polyhedron $P = \{x \in \mathbb{R}^n : Ax \leq b\}$ and an objective vector $c \in \mathbb{R}^n$.
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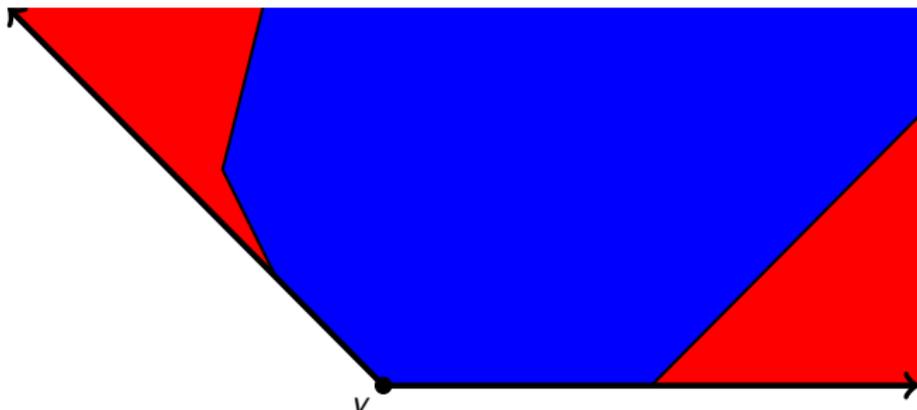
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- ▶ Consequence: exponential lower bounds for your favorite polytopes (TSP, Stable set, 3d matching, etc.) that correspond to hard problems.

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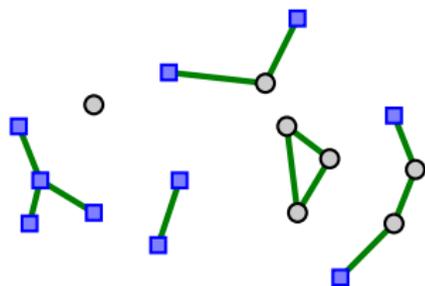
- ▶ Braun, Fiorini, Pokutta & Steurer showed that also the cut cone (radial cone of the cut polytope at vertex $\textcircled{0}$) has exponential extension complexity.
- ▶ Extension complexity of radial cones is inherited to projections and faces.
- ▶ Consequence: exponential lower bounds for your favorite polytopes (TSP, Stable set, 3d matching, etc.) that correspond to hard problems.

What remains?

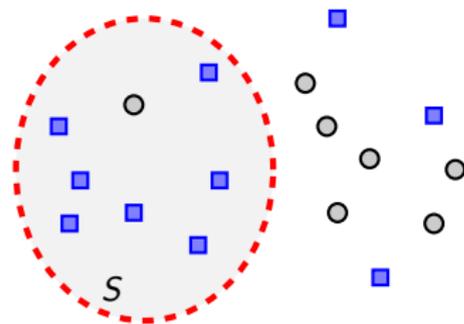
- ▶ Matching polytopes & friends ([this talk](#)).
- ▶ Stable-set polytopes of claw-free or perfect graphs.

Definitions ($K_n = (V_n, E_n)$ complete graph on n nodes; $T \subseteq V$, $|T|$ even):

- ▶ $J \subseteq E$ is a **T-join** if
 $|J \cap \delta(v)|$ is odd $\iff v \in T$

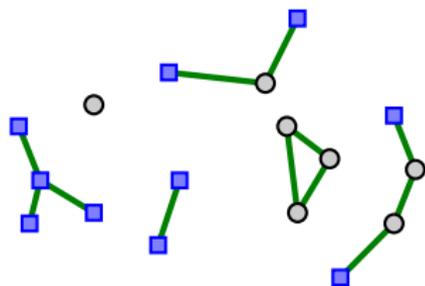


- ▶ $C = \delta(S) \subseteq E$ is a **T-cut** if
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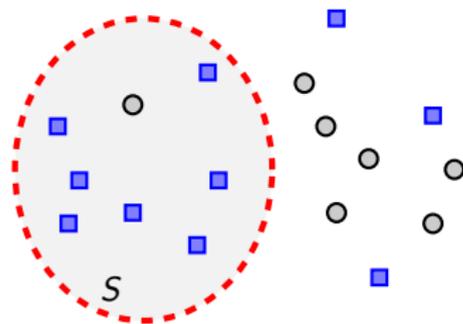


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Facts:

- ▶ Both minimization problems can be solved in polynomial time for $c \geq 0$.
- ▶ Each **T-join** J intersects each **T-cut** C in at least one edge:

$$|J \cap C| = \langle \chi(J), \chi(C) \rangle \geq 1$$

Polyhedra (Edmonds & Johnson, 1973):

▶ T -join Polyhedron $P_{T\text{-join}}(n)^\dagger$:

$$\begin{aligned} \langle \chi(C), x \rangle &\geq 1 && \text{for each } T\text{-cut } C \\ x_e &\geq 0 && \text{for each } e \in E \end{aligned}$$

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Relation to perfect matchings:

- ▶ A T -join $J \subseteq E$ is a perfect matching on nodes T if and only if $x = \chi(J)$ satisfies the valid inequalities $x_e \geq 0$ for all $e \in E \setminus E[T]$ and $\sum_{e \in \delta(v)} x_e \geq 1$ for all $v \in T$ with equality.

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Proposition (Walter & Weltge, 2018)

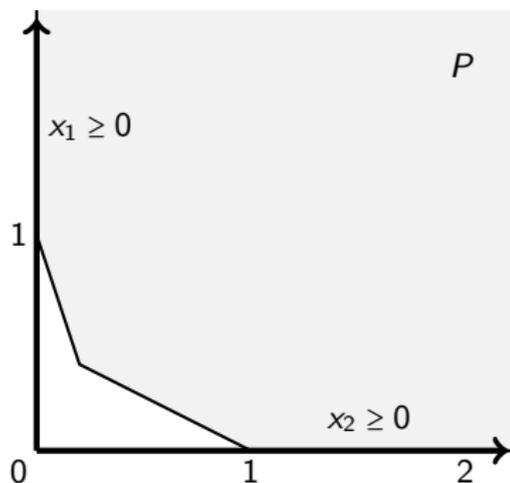
For every n and every set $T \subseteq V_n$, $x_C(P_{T\text{-join}}(n)^\uparrow) \leq \mathcal{O}(n^2 \cdot 2^{|T|})$.

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- ▶ Possible descriptions are:

$$P = \{x \in \mathbb{R}_+^d : \langle y^{(i)}, x \rangle \geq 1 \text{ for } i = 1, \dots, m\} \quad (y^{(1)}, \dots, y^{(m)} \in \mathbb{R}_+^d)$$

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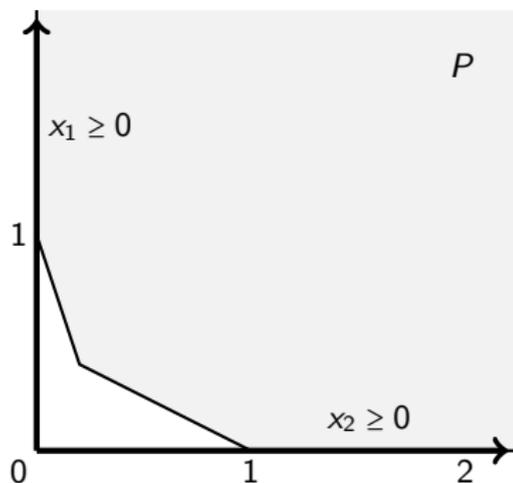
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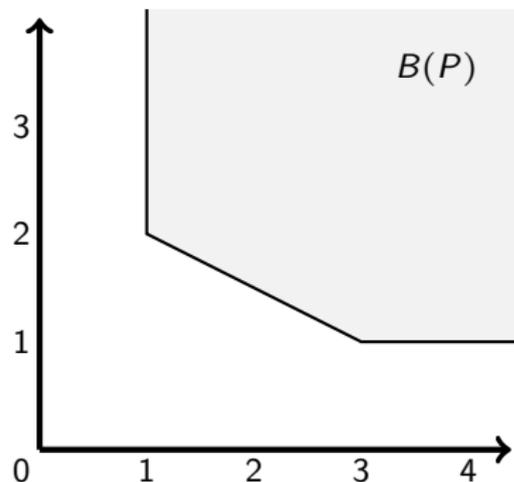
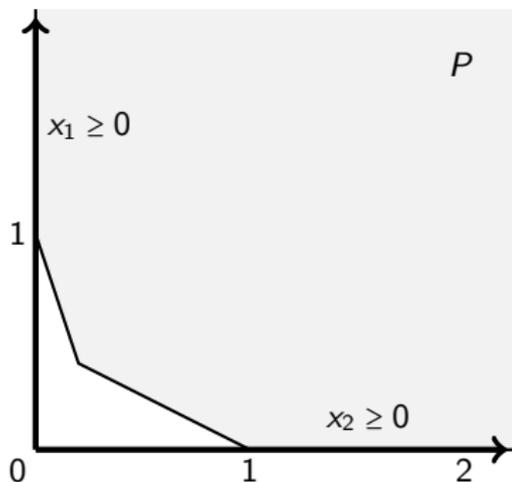
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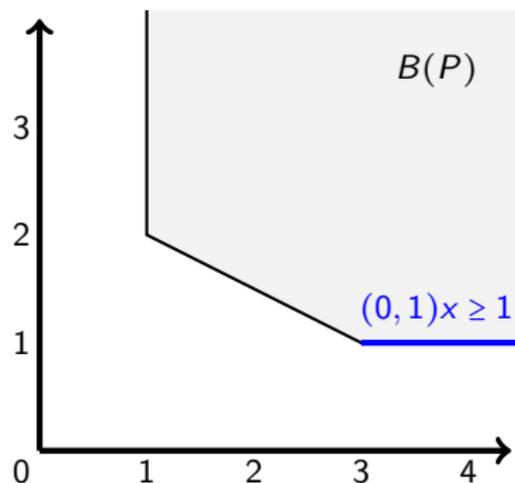
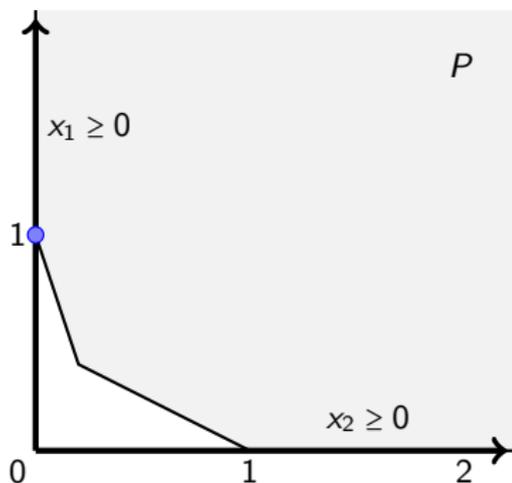
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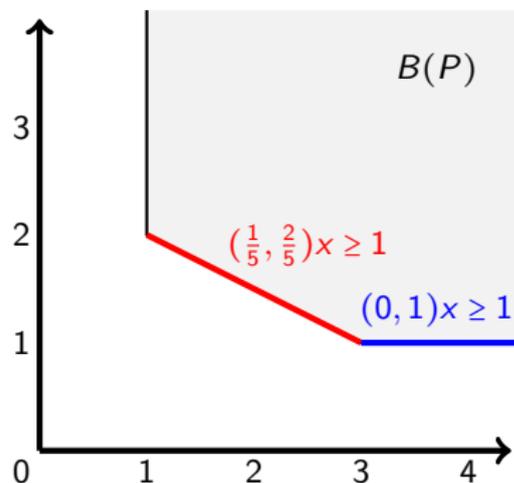
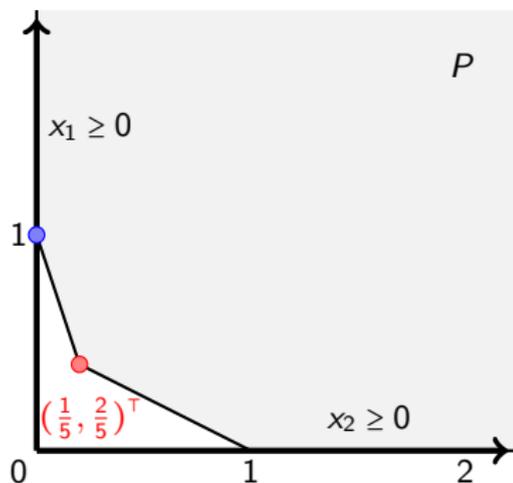
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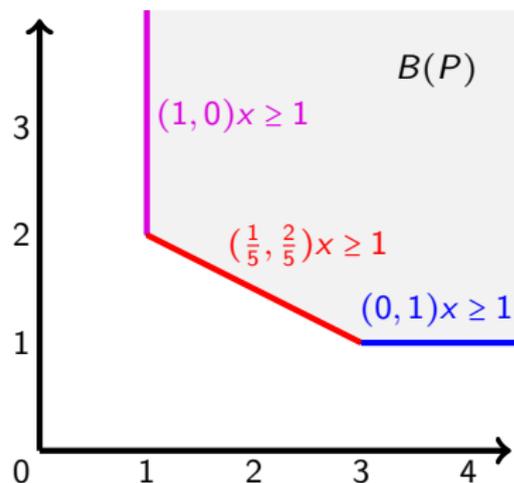
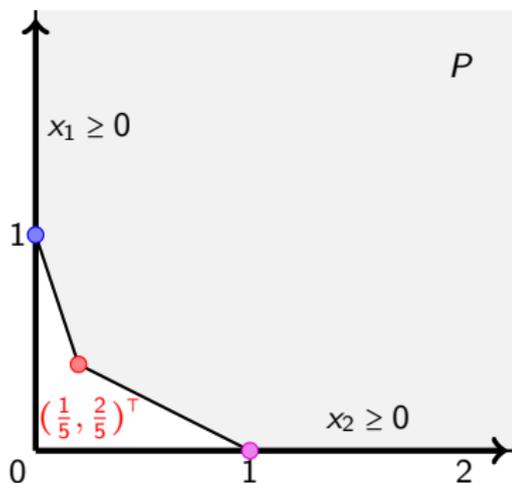
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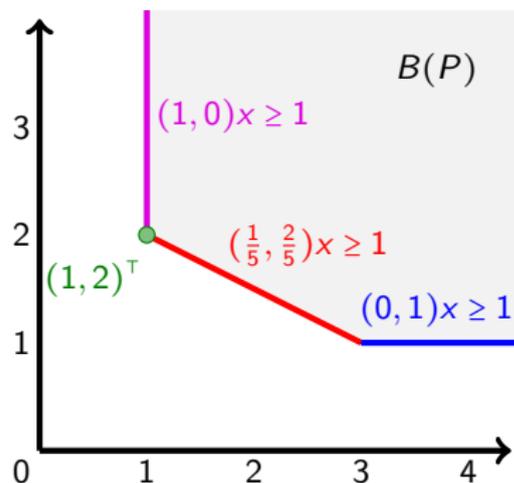
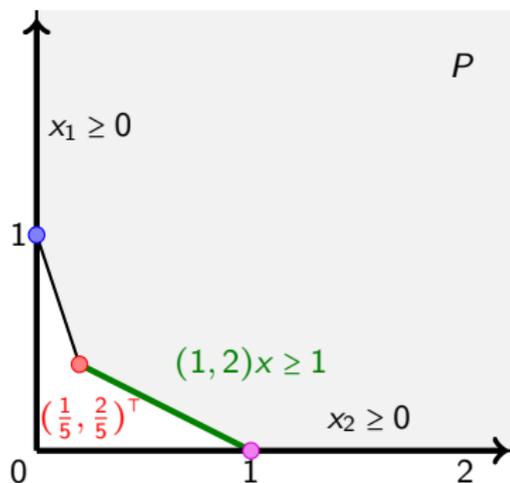
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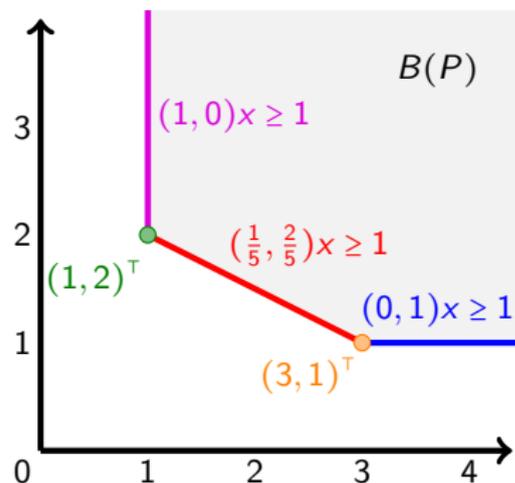
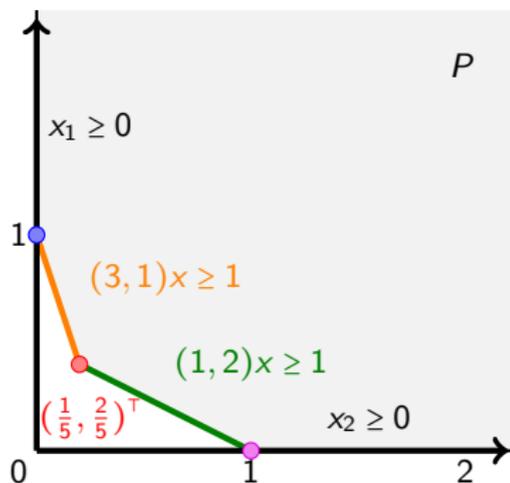
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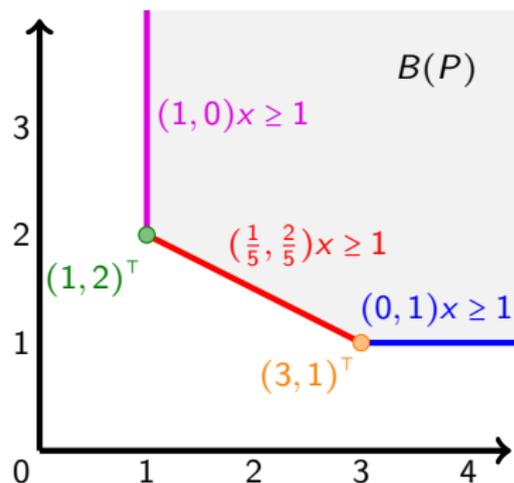
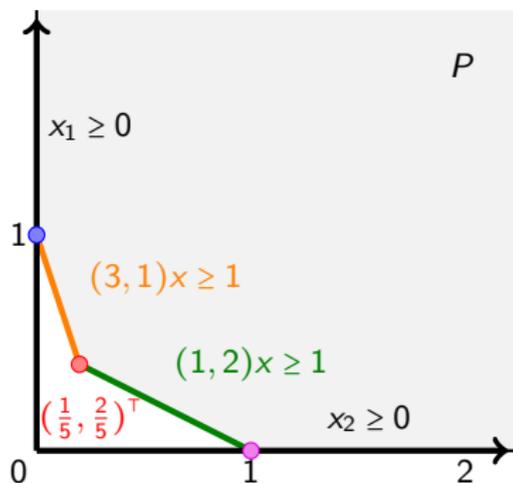
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- If P is blocking, then $B(B(P)) = P$.



Proposition (Martin, 1991; Conforti, Kaibel, Walter & Weltge, 2015)

Given a non-empty polyhedron Q and $\gamma \in \mathbb{R}$, let

$$P := \{x : \langle y, x \rangle \geq \gamma \text{ for all } y \in Q\}.$$

Then $\text{xc}(P) \leq \text{xc}(Q) + 1$.

Proof idea:

- ▶ Separation problem for inequalities is a linear program.
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- ▶ Any $v \in P$ defines a face $F_{B(P)}(v) := \{y \in B(P) : \langle v, y \rangle = 1\}$ of $B(P)$.

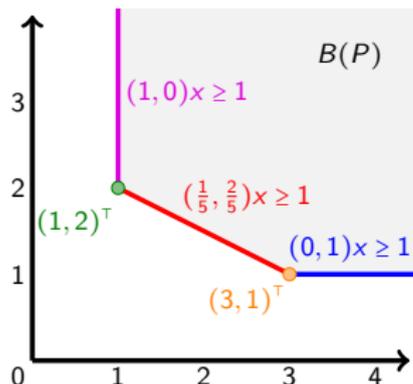
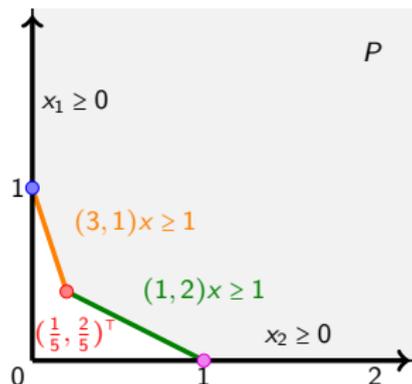
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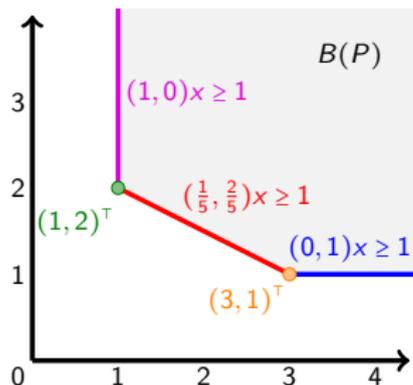
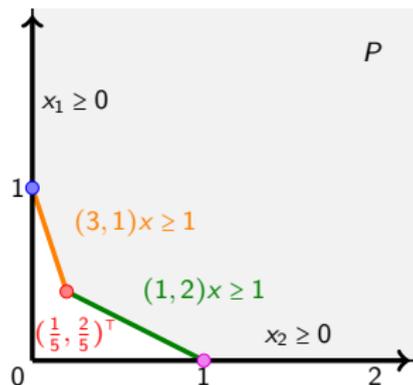
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Consequence:

- $xc(K_P(v))$ and $xc(F_{B(P)}(v))$ differ by at most 1.
- To prove lower or upper bounds on $xc(K_P(v))$, analyze $F_{B(P)}(v)$!

Theorem (Ventura & Eisenbrand, 2003)

For every set $T \subseteq V_n$ with $|T|$ even and every vertex v of $P_{T\text{-join}}(n)^\uparrow$, corresponding to a T -join $J \subseteq E_n$ in K_n , the extension complexity of the radial cone of $P_{T\text{-join}}(n)$ at v is most $\mathcal{O}(|J| \cdot n^2)$.

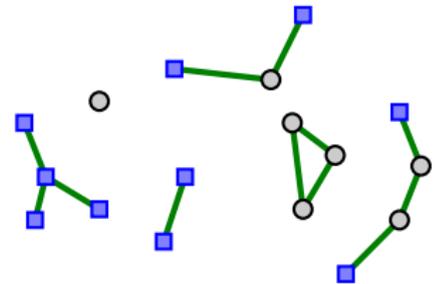
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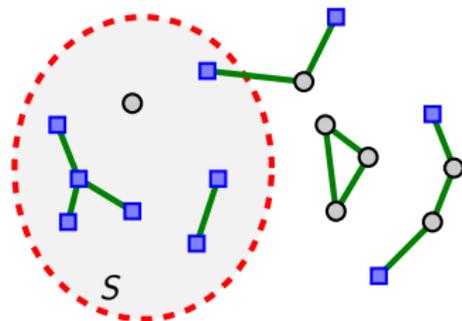
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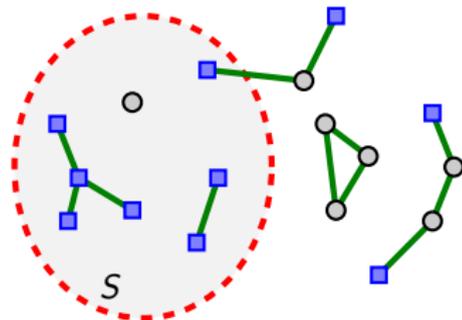
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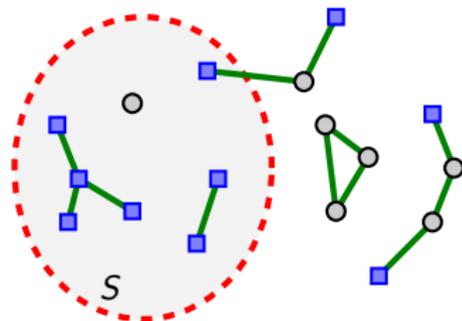
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- But F_m is also a face of $P_{T'\text{-cut}}(n)^\uparrow$ for $T' = m$ (set containing the nodes).



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For every set $T \subseteq V_n$ with $|T|$ even and every vertex v of $P_{T\text{-join}}(n)^\uparrow$, corresponding to a T -join $J \subseteq E_n$ in K_n , the extension complexity of the radial cone of $P_{T\text{-join}}(n)$ at v is most $\mathcal{O}(|J| \cdot n^2)$.

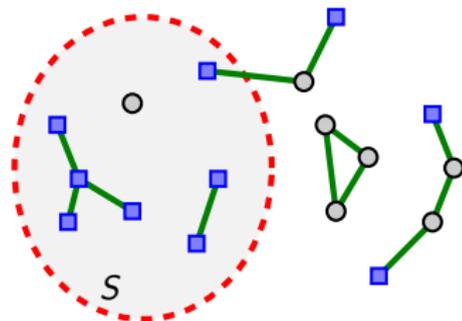
Their proof: ad-hoc construction using sets of flow variables.

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- By Lemma, theorem reduces to $\text{xc}(P)$ for

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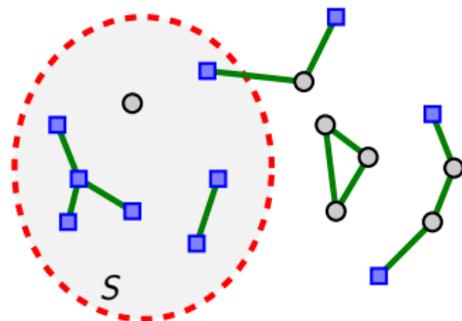
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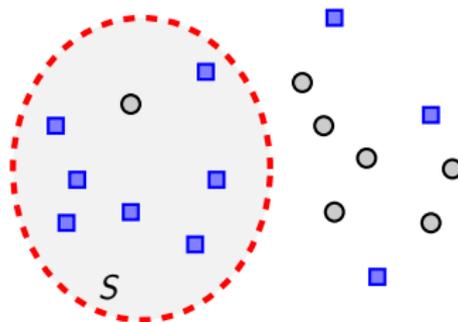
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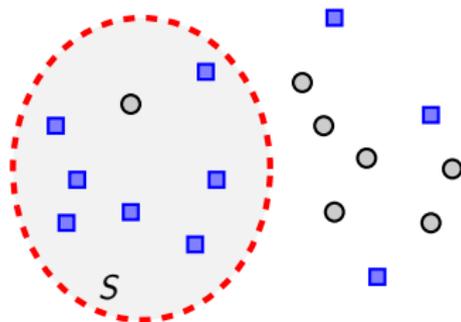


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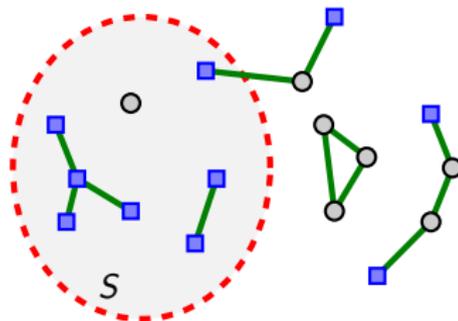
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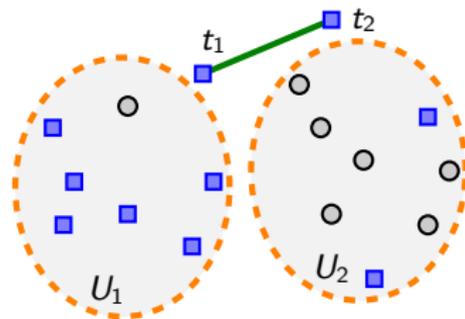
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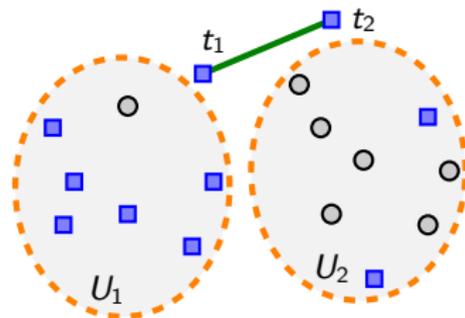
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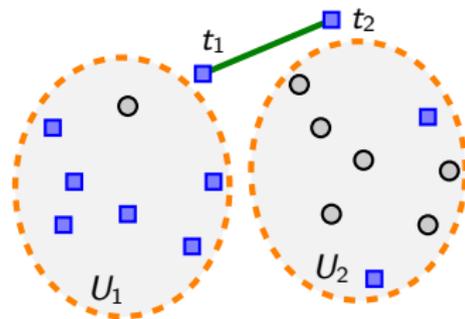
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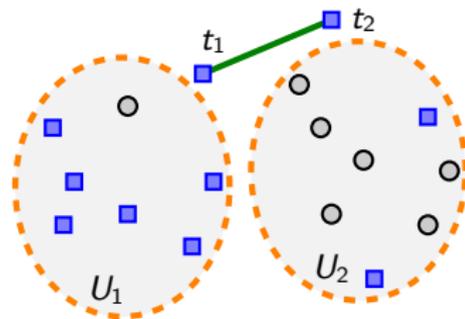
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Conclusion:

- ▶ Extended formulations can help, but only **sometimes**.
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Other candidates for investigation:

- ▶ Stable-set polytopes of claw-free graphs (current work with Gianpaolo Oriolo and Gautier Stauffer).
- ▶ Stable-set polytopes of perfect graphs (polyhedral description is known, but best (known) extended formulation has $\mathcal{O}(n^{\log n})$ facets).