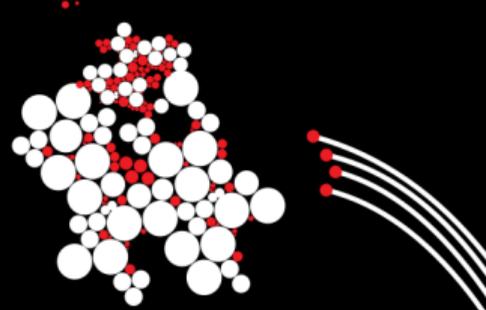


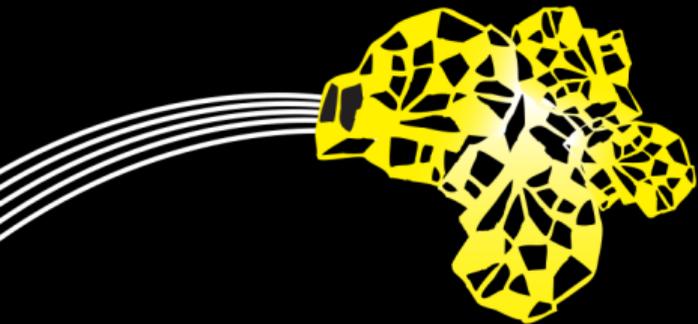
# UNIVERSITY OF TWENTE.

Common misbeliefs when working with total unimodularity



**Matthias Walter**

Research supported by NWO Grant OCENW.M20151



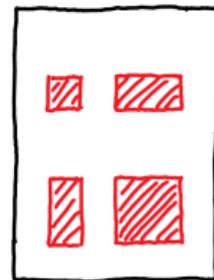
Aussois Combinatorial  
Optimization Workshop 2025



## Definition – Total unimodularity

A matrix is **totally unimodular (TU)** if every square submatrix has determinant  $-1, 0$  or  $+1$ .

Submatrices:



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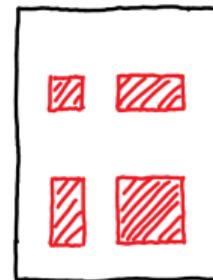
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## Proposition – TU-preserving operations

Total unimodularity is maintained under these operations:

- 1 Transposition
- 2 Permutation of rows or columns
- 3 Scaling rows or columns by  $-1$ .
- 4 Taking submatrices
- 5 Appending copies of rows or columns.
- 6 Appending unit rows or columns
- 7 **Pivoting**

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↓

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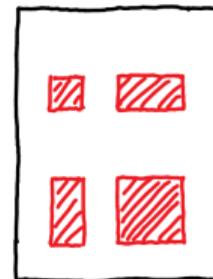
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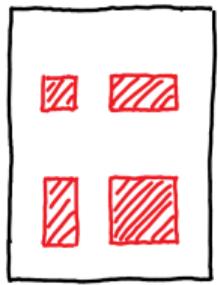
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## What again was pivoting?

► There was this thing called **pivot element** in Gaussian Elimination...

► So let's do elementary row operations:

$$\begin{bmatrix} -1 & 0 \\ 0 & 1 \\ 1 & 1 \end{bmatrix} \xrightarrow{\text{add row 1 to row 2}} \begin{bmatrix} -1 & 0 \\ -1 & 1 \\ 1 & 1 \end{bmatrix}$$

## Observation 1 – Pivoting $\neq$ elementary row operations

TU is not preserved by elementary row operations.

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A **pivot** on the top-left nonzero  $\alpha$  of a matrix  $A = \begin{bmatrix} \alpha & b^\top \\ c & D \end{bmatrix}$  yields the matrix  $A' = \begin{bmatrix} -\alpha^{-1} & \alpha^{-1}b^\top \\ \alpha^{-1}c & D - \alpha^{-1}cb^\top \end{bmatrix}$ .

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$$\begin{bmatrix} \mathbb{I} & A \end{bmatrix} = \begin{bmatrix} 1 & \mathbb{O}^T & \alpha & b^T \\ \mathbb{O} & \mathbb{I} & c & D \end{bmatrix} \xrightarrow{\text{scale row 1}} \begin{bmatrix} \alpha^{-1} & \mathbb{O}^T & 1 & \alpha^{-1}b^T \\ \mathbb{O} & \mathbb{I} & c & D \end{bmatrix} \xrightarrow{\text{subtract row 1 from others}}$$

$$\xrightarrow{\text{permute columns}} \begin{bmatrix} \alpha^{-1} & \mathbb{O}^T & 1 & \alpha^{-1}b^T \\ -\alpha^{-1}c & \mathbb{I} & \mathbb{O} & D - \alpha^{-1}cb^T \end{bmatrix} \xrightarrow{\text{permute columns}} \begin{bmatrix} 1 & \mathbb{O}^T & \alpha^{-1} & \alpha^{-1}b^T \\ \mathbb{O} & \mathbb{I} & -\alpha^{-1}c & D - \alpha^{-1}cb^T \end{bmatrix}$$

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A matrix  $A$  is **unimodular** if and only if ...

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## Folklore – TU and regularity of matroids

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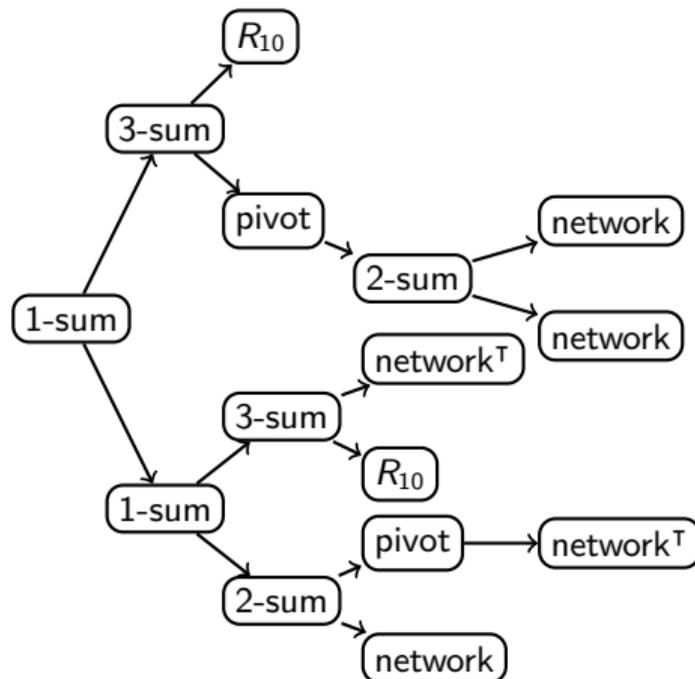
### Proposition – TU and regularity of matroids

A matrix  $A$  is totally unimodular if and only if the columns of  $\begin{bmatrix} \mathbb{I} & A \end{bmatrix}$  define a matroid  $\mathcal{M}$  that is a **linear matroid over every field**.

## Theorem – Seymour’s decomposition theorem

[Seymour '80]

A matrix is totally unimodular **if and only if** it arises from **network matrices** and copies of a particular 5-by-5-matrix  $R_{10}$  by TU-preserving operations and via  **$k$ -sums** for  $k = 1, 2, 3$ .



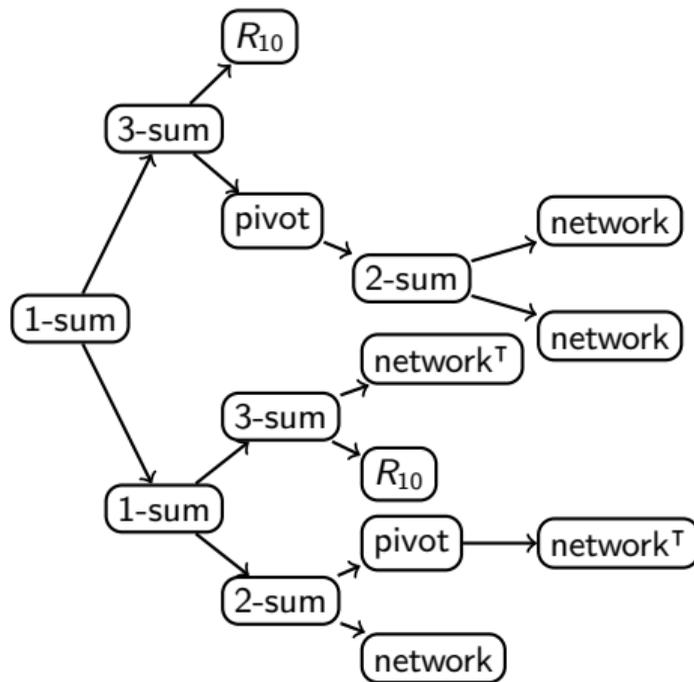
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### Exploited by several works:

- ▶ Seymour '80: *Decomposition of regular matroids*.
- ▶ Kashyap '08: *A decomposition theory for binary linear codes*.
- ▶ Dinitz & Kortsarz '12: *Matroid Secretary for Regular and Decomposable Matroids*.
- ▶ Artmann, Weismantel & Zenklusen '17: *A strongly polynomial algorithm for bimodular integer linear programming*.
- ▶ Aprile & Fiorini '21: *Regular Matroids Have Polynomial Extension Complexity*.
- ▶ Nägele, Santiago & Zenklusen '22: *Congruency-Constrained TU Problems Beyond the Bimodular Case*.
- ▶ Nägele, Nöbel, Santiago & Zenklusen 24'. *Advances on strictly  $\Delta$ -modular IPs*.



# Network matrices

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## Theorem – TU of node-arc incidence matrices

The coefficient matrix of flow balance constraints (1) of any digraph  $D = (V, A)$  is (totally) unimodular.

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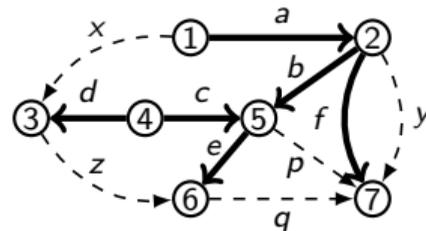
## Definition – Network matrices

[Tutte '65]

Let  $D = (V, A)$  be a directed graph and let  $T = (V, B)$  be a directed tree on  $V$ . The **network matrix** of  $(D, T)$  is the matrix  $M \in \{-1, 0, +1\}^{B \times A}$  whose entries  $M_{a,(v,w)}$  are

- ▶ +1 if the unique  $v$ - $w$ -path in  $T$  passes through  $a$  forwardly,
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## Digraph with directed tree:



	x	y	z	p	q
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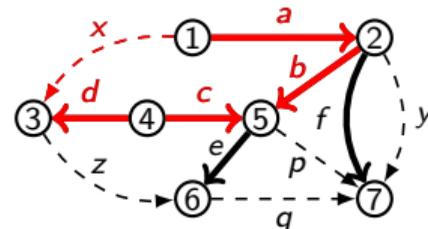
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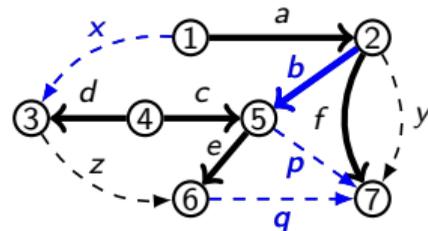
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## 1-sum

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### More flexible 3-sum definition:

$$\begin{bmatrix} A & a & a \\ c^\top & 0 & \varepsilon \end{bmatrix} \oplus_3 \begin{bmatrix} \varepsilon & 0 & b^\top \\ d & d & B \end{bmatrix} := \begin{bmatrix} A & ab^\top \\ dc^\top & B \end{bmatrix} \text{ for any } \varepsilon \in \{-1, +1\}$$

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### Catch:

- ▶ If we choose the right  $\varepsilon$ -value then TU is also preserved when decomposing.
- ▶ By negating  $a$ ,  $b$  and  $\varepsilon$  we obtain another 3-sum. There always exists one with  $\varepsilon = 1$ .
- ▶ Presented in Schrijver's '86 book, but only in the proof for decomposition algorithm.



## Recognition of matrix class:

- ▶ Unimodular / totally unimodular matrices
- ▶ Network matrices
- ▶ Equimodular matrices
- ▶ Balanced matrices (polytime is work in progress)

## Recognition of (binary / ternary) representation matrices of:

- ▶ Regular matroids
- ▶ Graphic matroids
- ▶ Series-parallel matroids



## Recognition of matrix class:

- ▶ Unimodular / totally unimodular matrices
- ▶ Network matrices
- ▶ Equimodular matrices
- ▶ Balanced matrices (polytime is work in progress)

## Recognition of (binary / ternary) representation matrices of:

- ▶ Regular matroids
- ▶ Graphic matroids
- ▶ Series-parallel matroids

## Future plans:

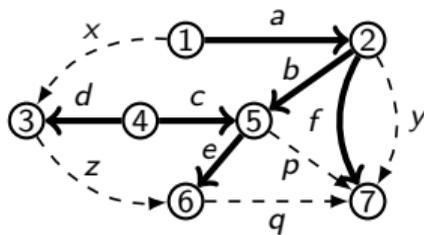
- ▶ Perfect matrices
- ▶ Consecutive 1s
- ▶ Max-flow-min-cut matroids
- ▶ More certificates (computing forbidden submatrices / minors)



## Example:

	$x$	$y$	$z$	$p$	$q$
$a$	1	0	0	0	0
$b$	1	0	0	-1	-1
$c$	-1	0	1	0	0
$d$	1	0	-1	0	0
$e$	0	0	1	0	-1
$f$	0	1	0	1	1

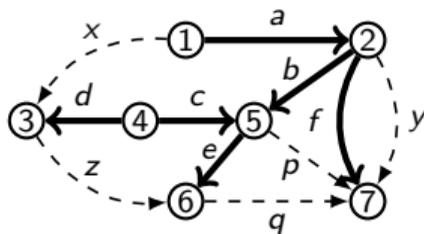
## Graph:



## Example:

	$x$	$y$	$z$	$p$	$q$
$a$	1	0	0	0	0
$b$	1	0	0	-1	-1
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## Graph:



## File input demo.dense:

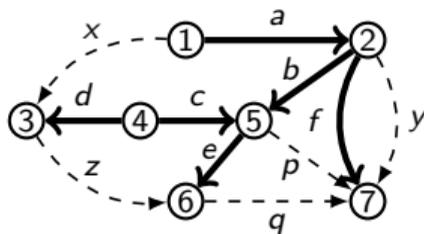
```

6 5
 1 0 0 0 0
 1 0 0 -1 -1
-1 0 1 0 0
 1 0 -1 0 0
 0 0 1 0 -1
 0 1 0 1 1

```

**Example:**

	<i>x</i>	<i>y</i>	<i>z</i>	<i>p</i>	<i>q</i>
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**Graph:****File input demo.dense:**

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6 5
 1 0 0 0 0
 1 0 0 -1 -1
-1 0 1 0 0
 1 0 -1 0 0
 0 0 1 0 -1
 0 1 0 1 1
```

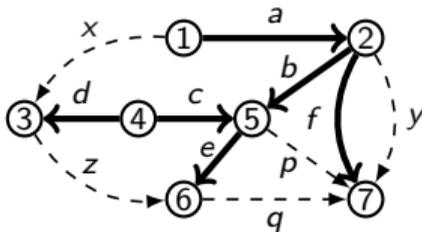
**Invocation:**

```
% cmr-network demo.dense -D demo.dot
Read 6x5 matrix with 13 nonzeros.
Matrix IS network.
Writing digraph to file <demo.dot>.
% dot -Tpdf demo.dot -o demo.pdf
```

## Example:

	x	y	z	p	q
a	1	0	0	0	0
b	1	0	0	-1	-1
c	-1	0	1	0	0
d	1	0	-1	0	0
e	0	0	1	0	-1
f	0	1	0	1	1

## Graph:

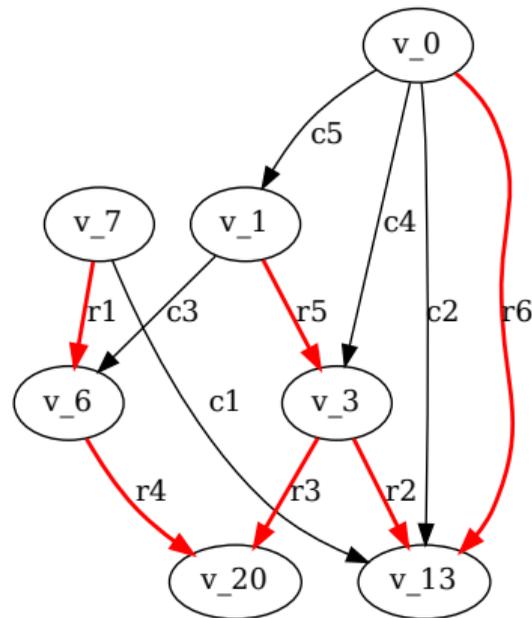


## File input demo.dense:

```
6 5
1 0 0 0 0
1 0 0 -1 -1
-1 0 1 0 0
1 0 -1 0 0
0 0 1 0 -1
0 1 0 1 1
```

## Invocation:

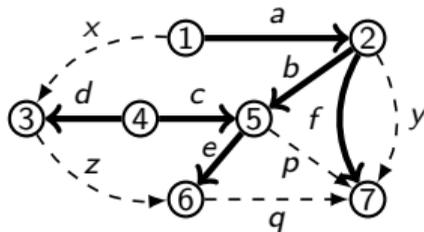
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## Graph:

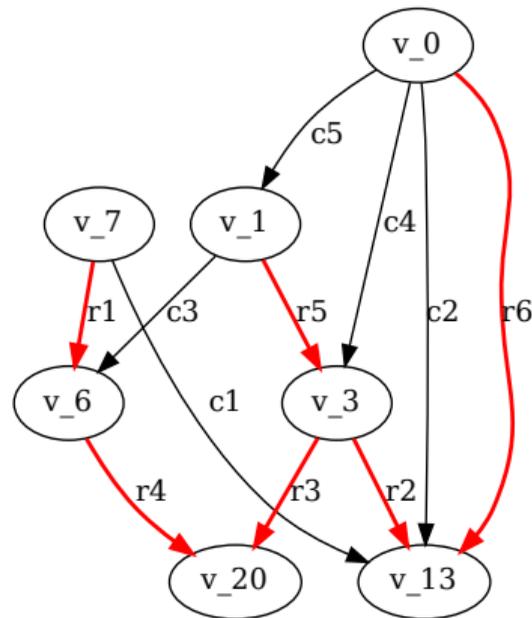


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```
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Coming soon:



SageMath interface to play around with Seymour decompositions in **Python**  
[joint work with Luze Xu and Matthias Köppe (both UC Davis)]

## New feature: Seymour decomposition

**Requirement:** Some algorithms rely on specific structure of decomposition!

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## Theorem – Computed Seymour decomposition

[Walter '25]

The recognition algorithm implemented in CMR returns (in polynomial time), for a given matrix  $M$ , either a submatrix  $N$  with  $|\det(N)| = 2$  or a decomposition tree with the following properties:

- ▶ There are multiple valid  $R_{10}$  leaf nodes that arise by pivoting and scaling rows/columns by  $-1$ .
- ▶ No explicit scaling or transposition nodes are needed.
- ▶ Pivot nodes appear only as parents of 3-sum nodes.
- ▶ A 1-sum node can have more children and will be the root.
- ▶ Series-parallel reductions, a special kind of 2-sums, are treated directly and more efficiently.
- ▶ If a node's matrix is a (transposed) network matrix then the node is a (transposed) network node.
- ▶ Every leaf node has at least 3 rows and 3 columns.

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- ▶ Every leaf node has at least 3 rows and 3 columns.

## Soon – Another 3-sum

Truemper defined an alternative 3-sum. There exists a decomposition tree with both 3-sum types but **no pivot** nodes.

## Observation 1 – Pivoting $\neq$ elementary row operations

TU is not preserved by elementary row operations.

## Observation 2 – Network matrices $\neq$ incidence matrices

Node-arc incidence matrices are a strict subset of network matrices!

## Observation 3 – Be careful with 3-sums!

TU is **not** preserved under 3-sum **decomposition**, but there always exists a suitable one that preserves TU.

## Observation 4 – TU only matters when you have additional variable bounds

Establish integrality of a polyhedron described by inequalities with integer right-hand side via **unimodularity**!  
Use **total unimodularity** (only) if you have bounds!

## Proposition – TU and regularity of matroids

A is TU if and only if the columns of  $\begin{bmatrix} \mathbb{I} & A \end{bmatrix}$  define a matroid that is a **linear matroid over every field**.

# Thank you!