Integer Programming Methods Homework set 4

Please conform to the following instructions:

- 1. Make the homework in groups of 2 or 3 persons.
- 2. Hand in you answers as pdf file.
 - (a) Use the tile "IntPM_Homework_Set_4_<groupname>.pdf".
 - (b) At the start of your file mention your names.
 - (c) The report must be clearly written, concise and complete.
- 3. Hand in your report by e-mail to <u>m.walter@utwente.nl</u>.

Exercise 1

Consider the Steiner tree problem for a graph G = (V, E) with terminals $T \subseteq V$ and edge costs $c \in \mathbb{R}^{E}_{\geq 0}$. Let D = (V, A) be the bidirected graph of G and let $r \in T$ be any root terminal. In the lecture we discussed the *undirected cut formulation*

$$\min \sum_{e \in E} c_e x_e \tag{1a}$$

s.t.
$$\sum_{e \in \delta(S)} x_e \ge 1$$
 $\forall S \subseteq V : r \in S, \ T \setminus S \neq \emptyset$ (1b)

$$x \in \mathbb{Z}_{\geq 0}^E \tag{1c}$$

in which variables x_e indicate whether edge $e \in E$ is bought ($x_e = 1$) or not ($x_e = 0$). Now consider the following *directed cut formulation* which exploits the following fact: every Steiner tree F can be "rooted away from r". This means, instead of the edge $\{u, v\} \in F$ we consider either the arc (u, v) or the arc (v, u), such that the unique r-v-path visits node u. Such a subgraph of D is called a **Steiner arborescence**.

$$\min \sum_{e \in E} c_e x_e \tag{2a}$$

s.t.
$$\sum_{a \in \delta^{\text{out}}(S)} y_a \ge 1 \qquad \forall S \subseteq V : r \in S, \ T \setminus S \neq \emptyset$$
(2b)

$$y_{(u,v)} + y_{(v,u)} \le x_{\{u,v\}} \quad \forall \{u,v\} \in E$$
 (2c)

$$y \in \mathbb{R}^A_{\ge 0} \tag{2d}$$

 $x \in \mathbb{Z}_{\geq 0}^{E} \tag{2e}$

(2f)

The goal of this exercise is to show that the directed formulation is strictly stronger than the undirected formulation (considering the projection on the *x*-variables).

- 1. Show that formulation (2) is always stronger than formulation (1).
- 2. Show that formulation (1) is *not* stronger than formulation (2). To this end, consider a triangle graph with all nodes being terminals and unit costs $c = (1, 1, 1)^{\intercal}$ and show that $x = (\frac{1}{2}, \frac{1}{2}, \frac{1}{2})^{\intercal}$ is feasible for the LP relaxation of (1) but not for the LP relaxation of (2).

Exercise 2

Construct a polyhedron P for which split cuts are stronger than Chvátal-Gomory cuts. To prove this, construct also an inequality $a^{\intercal}x \leq \beta$ that is a split cut but not implied by Chvátal-Gomory cuts.

Exercise 3

By Theorem 4.25 we know a perfect formulation for the minimum cost spanning tree problem on a graph G' = (V', E'), namely the spanning tree polytope

$$P_{\text{sptree}}(G') \coloneqq \text{conv}\{x^T \in \{0,1\}^{E'} : x^T \text{ incidence vector a spanning tree } T \text{ of } G'\}$$
(3)

is equal to

$$\{x \in \mathbb{R}^{E}_{\geq 0} : \sum_{e \in E'} x_e = |V'| - 1, \ \sum_{e \in E'[S]} x_e \leq |S| - 1 \ \forall \emptyset \neq S \subsetneqq V'\}$$

$$\tag{4}$$

holds. We consider the Subtour formulation for the Traveling Salesperson Problem for a graph G = (V, E).

$$\min \sum_{e \in E} c_e x_e \tag{5a}$$

s.t.
$$\sum_{e \in \delta(v)} x_e = 2$$
 $\forall v \in V$ (5b)

$$\sum_{e \in E[S]} x_e \le |S| - 1 \quad \forall S \subset V, \ 2 \le |S| \le |V| - 2$$
(5c)

$$x_e \ge 0 \qquad \forall e \in E \tag{5d}$$

Let $r \in V$ be an arbitrary node and let G' = (V', E') with $V' \coloneqq V \setminus \{r\}$ and $E' \coloneqq E \setminus \delta(r)$ be the subgraph of G obtained by removing r. Your goal is to prove that (5c) can be replaced by requiring that the restriction of x on the edge set E' is in the spanning-tree polytope of G', i.e., that the subtour relaxation of G is equal to the set of $x \in \mathbb{R}^E$ satisfying

$$\operatorname{proj}_{E'}(x) \in P_{\operatorname{sptree}}(G')$$
$$\sum_{e \in \delta(v)} x_e = 2 \qquad \forall v \in V$$
$$x_e \ge 0 \qquad \forall e \in E,$$

Remark: This implies that from any extended formulation of $P_{\text{sptree}}(G')$ of size k we can derive an extended formulation for the subtour relaxation of size $\mathcal{O}(k)$. In particular, there are such formulations with $k = \mathcal{O}(|V|)$ for planar graphs.