

# Integer Programming Methods

## Week 1

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# Prerequisite knowledge

- ▶ Linear algebra
- ▶ Linear programming
- ▶ Basic combinatorial optimization  
(shortest path problem, matching, maximum flow, etc.)
- ▶ Basic complexity theory
- ▶ Programming

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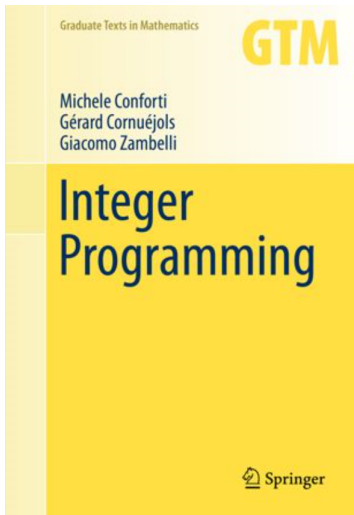
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Conforti, Cornuéjols, and Zambelli, *Integer programming*,  
Springer 2014, ISBN: 978-3-319-11008-0



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- ▶ 11 weeks.
- ▶ Per week:
  - ▶ Lecture
  - ▶ Read book
  - ▶ Homework
- ▶ Only 9 lectures, 2 spare lectures
- ▶ A **course schedule** can be found on the website.

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# Grading

- ▶ Grade is based on homework.
- ▶ Submit homework
  - ▶ in groups of 2-3,
  - ▶ by e-mail,
  - ▶ as pdf,
  - ▶ with title “IntPM\_Homework\_Set\_<X>\_<groupname>.pdf”,
  - ▶ and be sure to put your names in the file.

Homework Set	Deadline	Send to
1	December 4, 11:00	<a href="mailto:spliet@ese.eur.nl">spliet@ese.eur.nl</a>
2	January 22, 11:00	<a href="mailto:spliet@ese.eur.nl">spliet@ese.eur.nl</a>
3	February 5, 11:00	<a href="mailto:m.walter@utwente.nl">m.walter@utwente.nl</a>
4	February 19, 11:00	<a href="mailto:m.walter@utwente.nl">m.walter@utwente.nl</a>
5	March 4, 11:00	<a href="mailto:m.walter@utwente.nl">m.walter@utwente.nl</a>

- ▶ Each submission is awarded a score  $\in \{0, 0.5, 1, 1.5, 2\}$ .
- ▶ The final grade is the sum of the scores.

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# Integer linear programming

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# Integer linear program

## Definition

Let  $A \in \mathbb{Q}^{m \times n}$ ,  $b \in \mathbb{Q}^m$ ,  $c \in \mathbb{Q}^n$ . An **integer linear program (ILP)** is

$$\begin{aligned} \max \quad & \mathbf{c}^T \mathbf{x} \\ & A\mathbf{x} \leq \mathbf{b} \\ & \mathbf{x} \in \mathbb{N}_+. \end{aligned}$$

- ▶ The above ILP is in **canonical form**.
- ▶ ILP also includes
  - ▶ minimization, since  $\min \mathbf{c}^T \mathbf{x} = -\max -\mathbf{c}^T \mathbf{x}$ ,
  - ▶  $\geq$  constraints, since  $A\mathbf{x} \geq \mathbf{b} \Leftrightarrow -A\mathbf{x} \leq -\mathbf{b}$ ,
  - ▶ = constraints, since  $A\mathbf{x} = \mathbf{b} \Leftrightarrow A\mathbf{x} \leq \mathbf{b}$  and  $A\mathbf{x} \geq \mathbf{b}$ ,
  - ▶ negative valued variables, by using  $\mathbf{x} = \mathbf{x}^+ - \mathbf{x}^-$  for  $\mathbf{x}^+, \mathbf{x}^- \in \mathbb{N}_+$ .

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# Related problems

$$\begin{aligned} \max \quad & f(\mathbf{x}) \\ \mathbf{x} \in & X \end{aligned}$$

- ▶ **Linear programming (LP):**  
 $f$  is linear,  $X = \{\mathbf{x} \in \mathbb{R}^n : A\mathbf{x} \leq \mathbf{b}\}$ .
- ▶ **Integer linear programming (ILP):**  
 $f$  is linear,  $X = \{\mathbf{x} \in \mathbb{N}^m : A\mathbf{x} \leq \mathbf{b}\}$ .
- ▶ **Mixed integer linear programming (MILP):**  
 $f$  is linear,  $X = \{\mathbf{x} \in \mathbb{R}^n \times \mathbb{N}^m : A\mathbf{x} \leq \mathbf{b}\}$ .

(Non-linear problems:)

- ▶ **Integer programming (IP):**  $X \subseteq \mathbb{N}^n$ .
- ▶ **Mixed integer programming (MIP):**  $X \subseteq \mathbb{R}^n \times \mathbb{N}^m$ .

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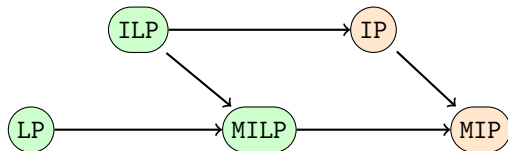
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# Special cases

✓ Many problems can be modelled as an ILP:

- ▶ the knapsack problem,
- ▶ the set packing problem,
- ▶ the set covering problem,
- ▶ the set partitioning problem,
- ▶ the traveling salesman problem,
- ▶ the generalized assignment problem,
- ▶ ...

! An algorithm for ILP would **solve all** these problems.

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# Complexity

## Theorem

*ILP is NP-hard*

## Proof.

- ▶ We create a polynomial time reduction of an NP-hard problem.
- ▶ **Subset sum** is the following NP-complete problem:

*Given  $\{w_1, \dots, w_n\} \subset \mathbb{N}$ , does any subset sum to  $W$ ?*

- ▶ Subset sum can be formulated as an ILP:

$$\begin{aligned} & \max 0 \\ & \sum_{i=1}^n w_i x_i = W \\ & x_i \in \{0, 1\} \quad \forall i \in \{1, \dots, n\} \end{aligned}$$



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- ✗ Never say:

*I can formulate my problem as an ILP, so it is NP-hard.*

- ▶ E.g. the shortest path problem is polynomially solvable and can be formulated as an ILP.

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# Branch-and-Bound

- ▶ **Branch-and-Bound** is an algorithm to solve an ILP.
  - ▶ **Branching** is used to go over all (relevant) solutions.
  - ▶ **Bounding** is used to avoid evaluating all solutions.
- ! We consider **maximization**.  
Branch-and-Bound similarly applies to minimization.
- ▶ Upper bounds are typically found using **relaxations**
  - ▶ Lower bounds might be found using **heuristics**.

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# Branch-and-Bound: Relaxations

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# Relaxations

## Definition

A **Relaxation** of a problem  $P$ , is a problem  $P'$  such that, every feasible solution of  $P$  is also feasible for  $P'$ , and has the same solution value.

- ▶ The solution value of a relaxation provides an **upper bound**.

## Theorem

Consider a problem  $P$  and its relaxation  $P'$ . If the optimal solution to  $P'$  is feasible for  $P$ , it is also optimal for  $P$ .

- ▶ Classical relaxations are:
  - ▶ Lagrangian relaxation
  - ▶ LP relaxation

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# Lagrangian relaxation

► ILP:

$$\begin{aligned} \max \mathbf{c}^T \mathbf{x} \\ A\mathbf{x} &\leq \mathbf{b} \\ D\mathbf{x} &\leq \mathbf{d} \\ \mathbf{x} &\in \mathbb{N}^n. \end{aligned}$$

► Lagrangian function:

$$\begin{aligned} \theta(\lambda) = \max \mathbf{c}^T \mathbf{x} + \lambda^T (\mathbf{d} - D\mathbf{x}) \\ A\mathbf{x} &\leq \mathbf{b} \\ \mathbf{x} &\in \mathbb{N}^n. \end{aligned}$$

✓ The Lagrangian relaxation is the upper bound

$$\min_{\lambda \geq 0} \theta(\lambda).$$

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# LP relaxation

► ILP:

$$\begin{aligned} \max \mathbf{c}^T \mathbf{x} \\ \mathbf{Ax} &\leq \mathbf{b} \\ \mathbf{x} &\in \mathbb{N}^n. \end{aligned}$$

► LP relaxation:

$$\begin{aligned} \max \mathbf{c}^T \mathbf{x} \\ \mathbf{Ax} &\leq \mathbf{b} \\ \mathbf{x} &\in \mathbb{R}^n. \end{aligned}$$

✓ The LP relaxation provides an upper bound.

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# Branch-and-Bound: Branching

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# Branching

**Branching is the splitting up of feasible space as follows:**

- ▶ Define the **feasible space**  $X = \{\mathbf{x} \in \mathbb{N}^n : A\mathbf{x} \leq \mathbf{b}\}$ .
- ▶ **Split up** the feasible space into  $\{X_1, \dots, X_k\}$ , such that
  - ▶  $X_i \subset X$ , for all  $i \in \{1, \dots, k\}$ ,
  - ▶  $X_i \cap X_j = \emptyset$ , for all  $i, j \in \{1, \dots, k\}$ ,  $i \neq j$ ,
  - ▶  $\bigcup_{i=1}^k X_i = X$ .

- ▶ Denote

$$z_i = \max\{\mathbf{c}^T \mathbf{x} : \mathbf{x} \in X_i\}$$

- ▶ It follows that

$$z = \max_{i \in \{1, \dots, k\}} \{z_i\}.$$

- ▶ The solution to the relaxation using  $X$  should be **infeasible** for all relaxations using  $X_i$ ,  $i \in \{1, \dots, k\}$ .

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# Branching - example

$$\begin{aligned} \max \quad & x_1 + 3x_2 \\ & x_1 + x_2 \leq 5 \\ & x_1 + 5x_2 \leq 15 \\ & x_1, x_2 \in \mathbb{N}_+ \end{aligned}$$

- ▶ The LP relaxation has solution  $x_1 = 2.5, x_2 = 2.5$ .
- ▶ This solution is not feasible (it is not integer).
- ▶ We could branch as follows:

$$X_1 = \{x \in \mathbb{N}_+^2 : x_1 + x_2 \leq 5, x_1 + 5x_2 \leq 15, x_1 \leq 2\}$$

$$X_2 = \{x \in \mathbb{N}_+^2 : x_1 + x_2 \leq 5, x_1 + 5x_2 \leq 15, x_1 \geq 3\}$$

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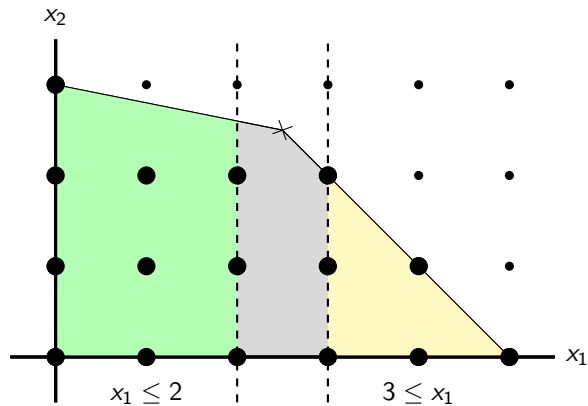
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# Branching - example



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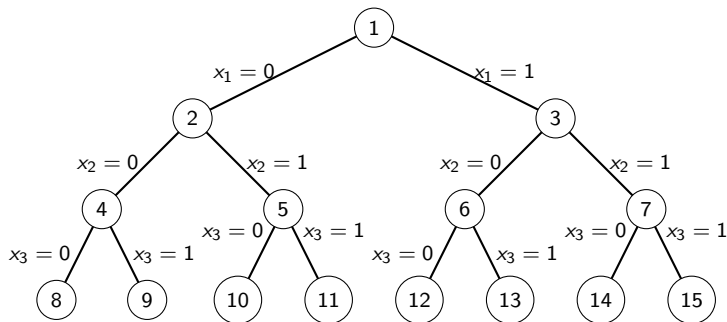
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## Branching tree:

(Also known as a search tree.)

- ▶ It is a **tree**.
- ▶ The **rootnode** corresponds to the ILP.
- ▶ The **child nodes** of each node are obtained by branching, i.e., they split up the corresponding problem.

**Branching tree example:**  $x \in \{0, 1\}^3$



# Branching

## Branching rule:

- ▶ is a rule that specifies how to **branch**,
- ▶ is used to generate a branching **tree**,
- ▶ guarantees that the **optimal** solution is found in one of the **leaf nodes** of the tree.

## Example:

- ▶ In each node solve the LP relaxation.
- ▶ Branching rule:
  - ▶ Select a variable with fractional value  $x = \alpha$ .
  - ▶ Create two children in which  $x \leq \lfloor \alpha \rfloor$  and  $\lceil \alpha \rceil \leq x$  are imposed.

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# Branch-and-Bound: Bounding

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- ✗ Creating the entire branching tree is time consuming.
- ✗ Evaluating all nodes in the branching tree time is consuming.
- ✓ We can limit the size of the branching tree by **pruning**:
  - ▶ Prune by infeasibility.
  - ▶ Prune by optimality.
  - ▶ Prune by bound.
- ▶ Typically we:
  - ▶ solve relaxations to get **upper bounds**,
  - ▶ use 'integer' solutions to relaxations as **lower bounds**,
  - ▶ or use heuristics to get **lower bounds**.

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**Branch-and-Bound:**

# Node selection

# Node selection

- ▶ **Processing** refers to solving the relaxation of a node.
- ▶ In each iteration of Branch-and-Bound, select an unprocessed node to be processed.
- ▶ Common **node selection strategies** are:
  - ▶ **Largest upper bound first**  
Select the unprocessed node with the largest upper bound.
  - ▶ **Deepest node first**  
Select the unprocessed node that is deepest in the tree, (farthest from the rootnode).

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# Summary of Branch-and-Bound

## **Branch-and-Bound is a framework.**

A Branch-and-Bound algorithm is obtained by choosing:

- ▶ A relaxation,
- ▶ A branching rule,
- ▶ A node selection strategy,
- ▶ A heuristic for lower bounds (not necessary).

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# Summary of Branch-and-Bound

Step 0 **Initialize** branching tree.

Step 1 **Terminate** if no unprocessed nodes remain.

Step 2 **Select** an unprocessed node.

Step 3 **Bound**.

Step 4 **Prune**

- ▶ If the current node is pruned by infeasibility or optimality, return to step 1.

Step 5 **Branch** and return to step 1.

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- ! The relaxation impacts the effectiveness of branch-and-bound:
  - ▶ the **speed** of computing the relaxed solution,
  - ▶ the **strength** of the bound.

✗ Never say:

*I made some ILP and my solver cannot find a solution fast,  
so heuristics are necessary.*

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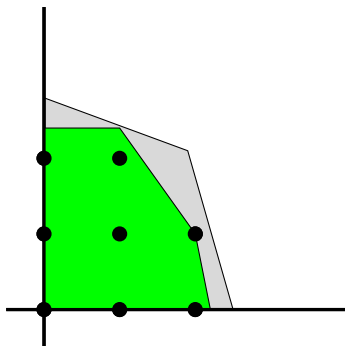
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- ▶ For (general) ILPs, the LP relaxation is important.
- ▶ The bound of the LP relaxation is called **LP bound**.



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## In this course we study

- ▶ the strength of LP relaxations,
- ▶ techniques to strengthen LP relaxations,
- ▶ algorithms to efficiently compute strong LP bounds,
- ▶ easy and difficult ILPs.

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